

**EAST Search History**

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S1	309	219/79	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/06 08:22
S2	63	S1 and ((multiaxial with transport\$3) or (multiaxial with transport\$3 robot))	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/06 08:25
S3	309	219/79	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/06 08:47
S5	30	S3 and (multi axial with transport\$3)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/06 08:48
S7	226	219/80	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/06 08:53
S12	30	S7 and (multi axi\$3 with transport\$3)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/06 08:55
S18	11	S7 and ((axi\$3) with (transport\$3 or robot \$2))	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/06 09:20
S19	226	219/80	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/06 14:43
S20	5	S19 and (multiple with robot\$2)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/06 14:44

S21	4	S19 and (transport with robot\$2)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/06 14:46
S30	226	219/80	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/08 15:24
S31	204	S30 and (multiaxial with transport) or (multiaxial with machine)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/08 15:24
S32	33	S30 and (multiaxial adj transport) or (multiaxial adj machine)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/08 15:28
S33	33	S30 and (multiaxial adj transport with robot) or (multiaxial adj machine)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/08 16:23
S34	33	S30 and (multiaxial adj transport adj robot) or (multiaxial adj machine)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/08 16:24
S35	282	(901/41).CCLS.	US-PGPUB; USPAT	OR	OFF	2008/10/10 15:06
S39	28260	("228").CLAS.	US-PGPUB; USPAT	OR	OFF	2008/10/14 07:58
S41	6	S39 and (multiaxial with transport\$ or multiaxial with robot\$)	US-PGPUB; USPAT	ADJ	ON	2008/10/14 08:00
S42	404	(901/42).CCLS.	US-PGPUB; USPAT	OR	OFF	2008/10/14 14:54
S43	1	S42 and (multiaxial with transport\$ or multiaxial with robot\$)	US-PGPUB; USPAT	ADJ	ON	2008/10/14 14:55
S44	404	(901/42).CCLS.	US-PGPUB; USPAT	OR	OFF	2008/10/15 09:53
S47	74	S44 and (multi axial with transport\$ or multiaxial with robot\$)	US-PGPUB; USPAT	OR	ON	2008/10/15 09:55
S48	283	(901/41).CCLS.	US-PGPUB; USPAT	OR	OFF	2008/10/16 14:01
S50	405	(901/42).CCLS.	US-PGPUB; USPAT	OR	OFF	2008/10/16 14:02

S53	41	(multiaxial with conveying with robot or multiaxial with processing)	US-PGPUB; USPAT	ADJ	ON	2008/10/16 14:04
S56	352	(219/158).CCLS.	US-PGPUB; USPAT	OR	OFF	2008/10/16 14:20
S57	1	S56 and (multiaxial with conveying with robot or multiaxial with processing)	US-PGPUB; USPAT	ADJ	ON	2008/10/16 14:21
S58	20	S56 and (welding robot)	US-PGPUB; USPAT	ADJ	ON	2008/10/16 15:10
S63	28262	("228").CLAS.	US-PGPUB; USPAT	OR	OFF	2008/10/20 15:16
S64	6	S63 and (multiaxial with transport\$ or multiaxial with robot\$)	US-PGPUB; USPAT	ADJ	ON	2008/10/20 15:16
S67	6	S63 and (multiax\$3 with transport\$ or multiax\$3 with robot\$)	US-PGPUB; USPAT	ADJ	ON	2008/10/20 15:26
S68	6	S63 and (multiax\$3 with transport\$ or multiax\$3 with robot\$)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2008/10/20 15:26
S69	0	219/79.ccls. and (multiax\$3 with transport\$ or multiax\$3 with robot\$)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2008/10/20 15:29
S70	353	219/79.ccls. and (multiax\$3 with transport\$) or (multiax\$3 with robot\$)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2008/10/20 15:30
S75	158	S70 and tool\$3	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2008/10/20 15:49
S77	40	S75 and carrier	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2008/10/20 15:50
S90	314	219/79	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/03/29 14:25

S91	13	((multiaxial with transport\$3) or (multiaxial with transport\$3)) with robot	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/03/29 15:15
S92	332	((multiaxial) or (multi-axial)) with robot	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/03/29 15:21
S93	6945	((multiaxial) or (multi-axial) or manipulator) with arm	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/03/29 16:22
S94	185	((multiaxial) or (multi-axial) or manipulator) with arm with tools	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/03/29 16:25
S95	120	((multiaxial) or (multi-axial) or manipulator) with arms with tools	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/04/07 09:46
S96	28648	("228").CLAS.	US_PGPUB; USPAT	OR	OFF	2009/04/07 10:38
S97	385	(901/41).CCLS.	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/04/07 10:44
S98	28707	("228") CLAS	US_PGPUB; USPAT	OR	OFF	2009/05/08 19:10
S99	7	S98 and (multiaxial with transport\$ or multiaxial with robot\$)	US_PGPUB; USPAT	ADJ	ON	2009/05/08 19:10
S101	122	((multiaxial) or (multi-axial) or manipulator) with arms with tools	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/05/08 19:12
S102	16	S101 with (weld\$3 or joint\$3)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/05/08 19:12
S103	222	S98 and ((axi\$3) with (transport\$3 or robot \$2))	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/05/08 20:23

S104	40	S103 and vehicle	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/05/08 20:26
S105	162051	robot support with (ball with socket with joint)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/05/09 13:25
S106	5	robot with support with (ball with socket with joint)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/05/09 13:25
S107	56212	S105 and arm	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/05/09 13:29
S108	55020	S107 and ((multiaxial with transport\$3) or (multiaxial with transport\$3 robot))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/05/09 13:29
S113	1363648	((multiaxial) or (multi-axial) or manipulator) with arms with bonding tool	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/05/09 15:44
S114	0	((multiaxial) or (multi-axial) or manipulator) with arms with (bonding adj tool)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/05/09 15:45
S115	7531	bonding tool\$3	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	OFF	2009/05/09 15:46
S116	3	S115 with robot	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	OFF	2009/05/09 15:46
S117	2	"20020007548"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/05/09 17:23
S118	448	(29/525.06).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/05/09 17:24

S119	5	robot with weld\$3 with inside with (vehicle body)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/05/09 17:49
S124	113	((multiaxial) or (multi-axial) or manipulator) with arms with clamp\$3	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/05/09 19:32
S125	40	robot with clamp\$3 with device with vehicle	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/05/09 19:41
S126	2	robot with clamp\$3 with inside with (vehicle body)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/05/09 19:54
S127	20	clamp\$3 with inside with outside with (vehicle body)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/05/09 20:00
S128	0	S121 and (clamp\$3 near inside near outside)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/05/09 20:03
S129	0	machin\$3 with clamp\$3 with inside with outside with (vehicle body)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/05/10 10:33
S130	8	machin\$3 with clamp\$3 with inside with outside with (vehicle body or interior)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/05/10 10:34

5/10/2009 12:31:23 PM

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